

Contents

Preface	ix
Foreword	x
Acknowledgements	xi
List of Symbols	xiii
I Mathematics and Physics	1
1 Mathematical Concepts	3
1.1 Arithmetic	3
1.2 Working with Algebraic Expressions	13
1.3 Quadratic Formula Derivation	24
1.4 Function Notation	26
1.5 Geometry	28
1.6 Trigonometry	52
1.7 Coordinate Systems	63
1.8 Simultaneous Equations	69
1.9 Triangulation	74
1.10 Calculus	76
1.11 Centroids and Average Values	95
2 Standards for Measurement	107
2.1 Measurement	107
2.2 Physical Quantities and Units of Measure	107
2.3 Accuracy and Precision	123
2.4 Numerical Precision	125
2.5 Quantifying Uncertainty	128

3	Vectors	131
3.1	Vector and Scalar Quantities	131
3.2	Vector Basics and Drawing Vectors	133
3.3	Length of a Vector	135
3.4	Vector Addition	137
3.5	Vector Subtraction	139
3.6	Vector Multiplication	140
3.7	Resolving a Vector into Components	145
4	Motion In One Dimension	149
4.1	The Study of Motion: Kinematics	149
4.2	Rectilinear Motion	151
4.3	Uniformly Accelerated Motion	157
4.4	Variable Acceleration	162
4.5	Relative Motion	174
5	Motion in More than One Dimension	179
5.1	Degrees of Freedom	179
5.2	Motion in Space	179
5.3	Displacement	181
5.4	Speed and Velocity	182
5.5	Acceleration	185
5.6	Uniform Projectile Motion	186
6	Dynamics and Newton's Laws of Motion	193
6.1	Newton's First Law	193
6.2	Newton's Second Law	194
6.3	The Concepts of Mass and Weight	195
6.4	Newton's Third Law	196
6.5	The Concept of Friction	196
6.6	Free Body Diagrams	198
6.7	The Concept of Torque	199
6.8	The Concept of Equilibrium	202
6.9	Center of Mass	207
6.10	Dynamic Weight Shift	215

7	Work and Energy	221
7.1	Work	221
7.2	Mechanical Energy	226
7.3	Conservation of Energy	229
7.4	Work–Energy Theorem	233
7.5	Derivation of the Kinetic Energy Formula	234
7.6	Power	236
8	Linear Momentum	245
8.1	Linear Momentum and Impulse	245
8.2	Conservation of Linear Momentum	251
8.3	In-Line Momentum	252
8.4	Elastic and Inelastic Collisions	257
8.5	The Presence of External Forces	263
9	Rotational Mechanics	273
9.1	Uniform Circular Motion	273
9.2	Lateral Acceleration	275
9.3	Rotational Motion	279
9.4	Mass Moment of Inertia	280
9.5	Newton’s Second Law for Rotation	286
9.6	Changing Torque and Gear Ratios	287
9.7	Rotational Kinetic Energy	290
9.8	Angular Momentum	292
9.9	Eccentric Collision Analysis Using Rotational Mechanics	302
II	Selected Topics in Traffic Crash Reconstruction	315
10	Friction and Acceleration Factors	317
10.1	Coefficient of Friction	317
10.2	Acceleration (Drag) Factor	318
10.3	Evidence of Maximum Friction	320
10.4	Determining Drag Factors	322
10.5	Effects of Uneven Braking on Drag Factor	326
10.6	Gathering Road Friction Data	328
10.7	Determining Drag Factors from Test Data	337
10.8	The Friction Circle and Lateral Friction	338

11 Speed Equations	341
11.1 Work–Energy Theorem	341
11.2 Basic Speed Equation	342
11.3 Multiple Surfaces	345
11.4 Combined Speed Equation	348
11.5 Work Done by Each Wheel	349
11.6 Adjusting the Drag Factor for a Changing Slope	354
11.7 Speed from a Spin Analysis	358
11.8 Rules For Combining Speeds	362
12 Time–Distance Relationships	371
12.1 Review of Definitions	371
12.2 Velocity Equations	372
12.3 Time Equations	379
12.4 Distance Equations	387
12.5 Acceleration and Drag Factor Equations	393
12.6 Acceleration Rate	401
12.7 Sample Time–Distance Work Problems	402
12.8 Perception–Response Time	418
13 Critical Speed Yaw	435
13.1 Definition of Critical Speed Yaw	435
13.2 Characteristics of the Tire Mark Evidence	436
13.3 Measuring Protocol for the Tire Mark Evidence	438
13.4 Determining the Lateral Acceleration Factor	442
13.5 Calculation Methodologies	446
13.6 Derivation of the Critical Speed Yaw Equation	453
13.7 Case Study	464
13.8 Nontraditional Critical Speed Yaw Analysis	470
14 Lane Change and Turn-Away Equations	475
14.1 Derivation of the Lane Change Equation	476
14.2 Turn-Away Equations	479
14.3 Using the Lane Change Equations	480
14.4 Speed Computations	484
14.5 A Comparison of Steady-State and Transient Behavior	485
14.6 Validation Testing	487

15 Airborne Analysis	491
15.1 Developing the Airborne Equation	491
15.2 Evidence of Projectile Trajectory	494
15.3 Magnitude and Direction of Velocity at Landing	496
15.4 Maximum Flight Height Attained if Takeoff Velocity Is Known	498
15.5 Horizontal Distance Traveled if Takeoff Velocity Is Known	499
15.6 Minimum Takeoff Speed–Same Landing Height	506
15.7 Minimum Take Off Speed for Any Height	509
15.8 Applications of Airborne Analysis	511
16 Collision Analysis Using Conservation of Linear Momentum	523
16.1 Introduction	523
16.2 Collision Types and Configurations	524
16.3 Collision Analysis Examples in One Dimension	525
16.4 Collision Analysis in Two Dimensions	531
16.5 Evidence Required for COLM Analysis	554
16.6 Special Considerations and Limitations	556
16.7 Summary	570
17 Collision Analysis Using Damage Momentum	575
17.1 Review of Conservation of Linear Momentum Analysis	575
17.2 Using Damage Momentum Analysis	577
17.3 In-Line Collisions Between Two Vehicles	583
17.4 Non-Central or Offset Collision Analysis	594
18 Damage (Crush) Collision Analysis	609
18.1 The General Energy Model	609
18.2 CRASH III Deformation Model	611
18.3 Calculating Δv Using the Effective Mass Ratio	633
18.4 Collision Forces and Collision Times	635
18.5 PDOF and Direction of Δv	639
18.6 Damage Profile Measuring Procedures	645
18.7 Crush Equation Summary	666
18.8 Limitations of Crush Analysis	669
19 Using Simultaneous Equations to Solve In-Line Collisions	675
19.1 Conservation of Linear Momentum	675
19.2 Energy Balance	680

19.3 Simultaneous Equations	685
19.4 Summary	689
20 Introduction to Rollover Analysis	691
20.1 Introduction	691
20.2 Rollover Taxonomy	692
20.3 Scene Evidence	695
20.4 Evidence from the Vehicle	697
20.5 Rollover Dynamics	707
20.6 Who was Driving?	715
20.7 Summary	716
A Off-Tracking In Low Speed Turns	717
A.1 Off-Tracking	717
A.2 Turning Geometry	719
A.3 Turning Radius	721
A.4 Calculating Off-Track Distance	726
A.5 Summary	736
B Vehicle Speed from Engine/Transmission Considerations	737
C Crush Energy Factors	739
Bibliography	741
Index	747